## SOLUTION TO A QUESTION ON A FAMILY OF IMPRIMITIVE SYMMETRIC GRAPHS

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## Abstract

We answer a recent question posed by Li *et al.* ['Imprimitive symmetric graphs with cyclic blocks', *European J. Combin.* **31** (2010), 362–367] regarding a family of imprimitive symmetric graphs.

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A graph  $\Gamma = (V, E)$  is called *G*-symmetric if  $\Gamma$  admits *G* as a group of automorphisms such that *G* is transitive on *V* and on the set of arcs of  $\Gamma$ , where an *arc* is an ordered pair of adjacent vertices. If in addition  $\Gamma$  admits a *nontrivial G*-invariant partition, that is, a partition  $\mathcal{B}$  of *V* such that  $1 < |\mathcal{B}| < |V|$  and  $\mathcal{B}^g := \{\alpha^g : \alpha \in B\} \in \mathcal{B}$  for  $\mathcal{B} \in \mathcal{B}$  and  $g \in G$ , then  $\Gamma$  is called an *imprimitive G*-symmetric graph. In this case the *quotient* graph  $\Gamma_{\mathcal{B}}$  of  $\Gamma$  with respect to  $\mathcal{B}$  is defined to have vertex set  $\mathcal{B}$  such that  $\mathcal{B}, C \in \mathcal{B}$  are adjacent if and only if there exists at least one edge of  $\Gamma$  between  $\mathcal{B}$  and C. We assume that  $\Gamma_{\mathcal{B}}$  contains at least one edge, so that each block of  $\mathcal{B}$  is an independent set of  $\Gamma$ . Denote by  $\Gamma(\alpha)$  the neighbourhood of  $\alpha \in V$  in  $\Gamma$ , and define  $\Gamma(X) = \bigcup_{\alpha \in X} \Gamma(\alpha)$  for  $X \in \mathcal{B}$ . For blocks  $\mathcal{B}, C \in \mathcal{B}$  adjacent in  $\Gamma_{\mathcal{B}}$ , let  $\Gamma[\mathcal{B}, C]$  be the bipartite subgraph of  $\Gamma$ induced on  $(\mathcal{B} \cap \Gamma(C)) \cup (C \cap \Gamma(\mathcal{B}))$ . Then  $\Gamma[\mathcal{B}, C]$  is independent of the choice of  $(\mathcal{B}, C)$  up to isomorphism. Define

$$v := |B|$$
 and  $k := |B \cap \Gamma(C)|$ 

to be the block size of  $\mathcal{B}$  and the size of each part of the bipartition of  $\Gamma[B, C]$ , respectively.

In line with a geometrical approach suggested in [1], various situations may occur for  $\Gamma$ , G,  $\Gamma_{\mathcal{B}}$ ,  $\Gamma[B, C]$  and a certain 1-design with point set B; see, for example, [1, 3, 5–7]. The case where  $k = v - 2 \ge 1$  was studied in [2, 4] and a necessary and sufficient condition for  $\Gamma_{\mathcal{B}}$  to be (G, 2)-arc-transitive was given in [2]. In this case, the multigraph  $\Gamma^{B}$  [2] with vertex B and an edge joining the two vertices of  $B \setminus \Gamma(C)$  for every  $C \in \Gamma_{\mathcal{B}}(B)$  plays an important role in the structure of  $\Gamma$  and  $\Gamma_{\mathcal{B}}$ ,

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where  $\Gamma_{\mathcal{B}}(B)$  is the neighbourhood of B in  $\Gamma_{\mathcal{B}}$ . Since  $\Gamma$  is G-symmetric, up to isomorphism  $\Gamma^B$  is independent of the choice of B, and the multiplicity of each edge { $\alpha$ ,  $\beta$ } of  $\Gamma^B$ , namely

$$m := |\{C \in \Gamma_{\mathcal{B}}(B) : B \setminus \Gamma(C) = \{\alpha, \beta\}\}|,$$

is independent of the choice of  $\{\alpha, \beta\}$ . Denote by Simple( $\Gamma^B$ ) the underlying simple graph of  $\Gamma^B$  and by  $G_B$  the setwise stabilizer of B in G. It has been proved [2, Theorem 2.1] that Simple( $\Gamma^B$ ) is  $G_B$ -vertex-transitive and  $G_B$ -edge-transitive, and either  $\Gamma^B$  is connected or v is even and Simple( $\Gamma^B$ ) is a perfect matching  $(v/2) \cdot K_2$ . In the latter case detailed information about  $\Gamma$  was obtained in [2, Theorem 1.3] when  $\Gamma^B$  is simple. In [4], Li *et al.* proved that, if Simple( $\Gamma^B$ ) is a cycle, then v must be small, namely v is equal to 3 or 4. Based on this they posed the following question.

QUESTION 1. In the case where k = v - 2 and  $\Gamma^B$  is connected, is v bounded by some function of the valency of Simple( $\Gamma^B$ )?

Define

$$b := \operatorname{val}(\Gamma_{\mathcal{B}}), \quad s := \operatorname{val}(\Gamma[B, C]), \quad r := |\{C \in \mathcal{B} : \alpha \in \Gamma(C)\}|$$

to be respectively the valency of  $\Gamma_{\mathcal{B}}$ , the valency of  $\Gamma[B, C]$ , and the number of blocks of  $\mathcal{B}$  that contain at least one neighbour of a fixed vertex  $\alpha \in V$  in  $\Gamma$ . Note that v, k, b, r and s all rely on the G-invariant partition  $\mathcal{B}$ .

In this paper we answer Question 1 by proving the following stronger result: there are only two possibilities for Simple( $\Gamma^B$ ) and v can take two values only.

THEOREM 2. Suppose that  $\Gamma$  is a G-symmetric graph which admits a nontrivial *G*-invariant partition  $\mathcal{B}$  such that  $k = v - 2 \ge 1$ ,  $\Gamma_{\mathcal{B}}$  is connected and  $\text{Simple}(\Gamma^{B})$ is connected with valency  $d \ge 2$ . Then one of the following occurs.

- (a)
- Simple( $\Gamma^B$ )  $\cong K_v$ , v = d + 1, b = m(v 1)v/2, and  $G^B_B$  is 2-homogeneous. Simple( $\Gamma^B$ )  $\cong K_{v/2,v/2}$ , v = 2d,  $b = mv^2/4$ , and the bipartition of (b) Simple( $\Gamma^B$ ) induces a *G*-invariant partition  $\mathcal{B}^*$  of the vertex set of  $\Gamma$  (which is a refinement of  $\mathcal{B}$ ) such that one of the following holds for its parameters:
  - (i)  $v^* = k^* + 1 = v/2, b^* = b, r^* = r, s^* = s;$
  - (ii)  $v^* = k^* + 1 = v/2, b^* = 2b, r^* = 2r, s^* = s/2;$
  - (iii)  $v^* = 2k^* + 1 = v/2, b^* = 2b, r^* = r, s^* = s.$

**PROOF.** Suppose that  $\Gamma$ , G and B satisfy the conditions in the theorem. Denote  $\Omega := \text{Simple}(\Gamma^B)$ . Let B and C be two blocks of B adjacent in  $\Gamma_B$ , and let  $\{\alpha, \beta\} = B \setminus \Gamma(C)$  be the corresponding edge of  $\Omega$ . Define

$$U := (\Omega(\alpha) \cup \Omega(\beta)) \setminus \{\alpha, \beta\}$$

to be the neighbourhood of the subset  $\{\alpha, \beta\}$  of B in  $\Omega$ , and set

$$W := B \setminus (U \cup \{\alpha, \beta\}).$$

Since  $\Omega$  has valency  $d \ge 2$ , we have  $U \ne \emptyset$ . Since every element of  $G_{BC}$  (=  $(G_B)_C$ ) fixes  $\{\alpha, \beta\}$  setwise, it follows that every element of  $G_{BC}$  fixes each of U and W setwise. Thus  $G_{BC} \le G_U \cap G_W$ .

*Claim 1.*  $W = \emptyset$ , that is,  $U = B \setminus \{\alpha, \beta\}$ , or every vertex in *B* is adjacent to at least one of  $\alpha$  and  $\beta$  in  $\Omega$ .

Suppose otherwise and let  $\delta \in W$ . Since  $U \neq \emptyset$ , we may take a vertex  $\gamma \in U$ . Since  $\delta$ ,  $\gamma \neq \alpha$ ,  $\beta$ , there exist  $\delta_1$ ,  $\gamma_1 \in C$  adjacent to  $\delta$ ,  $\gamma$  in  $\Gamma$ , respectively. (It may occur that  $\delta_1 = \gamma_1$ .) Since  $\Gamma$  is *G*-symmetric, there exists  $g \in G$  such that  $(\gamma, \gamma_1)^g = (\delta, \delta_1)$ . Since *g* maps  $\gamma \in B$  to  $\delta \in B$  and  $\gamma_1 \in C$  to  $\delta_1 \in C$ , it fixes *B* and *C* setwise. Hence  $g \in G_{BC} \leq G_U \cap G_W$ . However, this is a contradiction, because *g* maps  $\gamma \in U$  to  $\delta \in W$ . Therefore  $W = \emptyset$  as claimed.

Since  $\Omega$  has valency d, by Claim 1,  $d - 1 \le |U| \le 2(d - 1)$ . Since v = |U| + 2 by Claim 1, it follows that

$$d+1 \le v \le 2d.$$

Claim 2. In  $\Omega$  any two adjacent vertices have 2d - v common neighbours, and two nonadjacent vertices have the same neighbourhood.

In fact, since  $\Omega$  is  $G_B$ -edge-transitive [2, Theorem 2.1], the number  $\lambda$  of common neighbours of a pair of adjacent vertices in  $\Omega$  is a constant. Consider the neighbourhood U of  $\{\alpha, \beta\}$  in  $\Omega$ , where  $\alpha$  and  $\beta$  are as above. There are exactly  $d - \lambda - 1$  vertices in B which are adjacent to  $\alpha$  but not  $\beta$  ( $\beta$  but not  $\alpha$ , respectively). Thus, by Claim 1,  $2(d - \lambda - 1) + \lambda = v - 2$ , which implies that  $\lambda = 2d - v$ .

Now let  $\sigma$  and  $\tau$  be any two nonadjacent vertices of  $\Omega$ . If  $\gamma \in B$  is adjacent to  $\sigma$  in  $\Omega$ , then by applying Claim 1 to the edge  $\{\sigma, \gamma\}$ , every vertex in B is adjacent to either  $\sigma$  or  $\gamma$  in  $\Omega$ . Thus, since  $\tau$  is not adjacent to  $\sigma$ , it must be adjacent to  $\gamma$  in  $\Omega$  and so  $\Omega(\sigma) \subseteq \Omega(\tau)$ . Similarly,  $\Omega(\tau) \subseteq \Omega(\sigma)$ . Hence  $\Omega(\sigma) = \Omega(\tau)$  and Claim 2 is proved.

Consider any maximal (with respect to set-theoretic inclusion) independent set X of  $\Omega$ . By Claim 2 the vertices in X have the same neighbourhood in  $\Omega$ . Denote this common neighbourhood by Y, so that |Y| = d. If  $B \setminus (X \cup Y) \neq \emptyset$ , then by the maximality of X, any vertex in  $B \setminus (X \cup Y)$  must be adjacent to at least one vertex  $\delta \in X$  in  $\Omega$ , which implies that  $\delta$  is adjacent to d + 1 vertices in  $\Omega$ . This contradiction shows that  $X \cup Y = B$  and consequently |X| = v - d. Since this holds for any maximal independent set of  $\Omega$  and since  $\Omega$  is  $G_B$ -vertex-transitive, we have the following claim.

Claim 3. v - d divides d and  $\Omega$  is a complete t-partite graph with each part containing v - d vertices, where t = v/(v - d).

Based on this we now prove the following claim.

Claim 4.  $\Omega \cong K_v$  or  $K_{v/2,v/2}$ ; that is, t = v or 2.

Suppose to the contrary that 2 < t < v. Denote by  $B^1, B^2, \ldots, B^t$  the parts of the *t*-partition of  $\Omega$ . Similarly, for any  $D \in \mathcal{B}$ , denote by  $D^1, D^2, \ldots, D^t$  the parts of the *t*-partition of Simple( $\Gamma^D$ ) ( $\cong \Omega$ ). Set

$$\mathcal{B}^* := \{ D^1, D^2, \ldots, D^t : D \in \mathcal{B} \}.$$

It is straightforward to verify that  $\mathcal{B}^*$  is a nontrivial *G*-invariant partition of the vertex set of  $\Gamma$  and that  $\mathcal{B}^*$  is a refinement of  $\mathcal{B}$ . For adjacent  $B, C \in \mathcal{B}$  and  $\{\alpha, \beta\} = B \setminus \Gamma(C)$  as above,  $\alpha$  and  $\beta$  belong to different parts of  $\Omega$ , and so we may assume that  $\alpha \in B^1$  and  $\beta \in B^2$  without loss of generality. Since t < v, each part of  $\Omega$  has size at least two and hence we can take a vertex  $\xi \in B^2 \setminus \{\beta\}$ . Since t > 2,  $\Omega$  has at least three parts and so we can take a vertex  $\eta \in B^3$ . Since  $B \setminus \Gamma(C) = \{\alpha, \beta\}$  and  $\xi, \eta \neq \alpha, \beta$ , each of  $\xi$  and  $\eta$  has at least one neighbour in *C*. Let  $\xi$  be adjacent to  $\gamma \in C$ and  $\eta$  adjacent to  $\delta \in C$ . Since  $\Gamma$  is *G*-symmetric, there exists an element  $g \in G$  which maps  $(\eta, \delta)$  to  $(\xi, \gamma)$ . Thus  $g \in G_{BC}$ . Since  $\mathcal{B}^*$  is *G*-invariant and *g* maps  $\eta \in B^3$  to  $\xi \in B^2$ , *g* should map  $B^3$  to  $B^2$ . Since every vertex in  $B^3$  has a neighbour in *C*, it follows that every vertex in  $B^2$  has a neighbour in *C*. However, this is a contradiction since  $\beta \in B^2$  has no neighbour in *C*. Therefore we have proved Claim 4.

Obviously, if  $\Omega \cong K_v$ , then d = v - 1, b = mdv/2 = m(v - 1)v/2, and moreover  $G_B$  is 2-homogeneous on B since  $\Omega$  is  $G_B$ -edge-transitive by [2, Theorem 2.1].

In the case  $\Omega \cong K_{v/2,v/2}$ , we have d = v/2,  $b = mdv/2 = mv^2/4$ , and the *G*-invariant partition  $\mathcal{B}^*$  above becomes  $\mathcal{B}^* = \{D^1, D^2 : D \in \mathcal{B}\}$ . Obviously,  $\mathcal{B}^*$  is a nontrivial partition of the vertex set of  $\Gamma$  and is a refinement of  $\mathcal{B}$ . In the case where each of  $\Gamma(B^1)$  and  $\Gamma(B^2)$  has nonempty intersection with exactly one of  $C^1$  and  $C^2$ , it is easy to see that  $v^* = k^* + 1$ ,  $b = b^*$ ,  $r = r^*$  and  $s = s^*$ , and so case (b)(i) occurs. In the remaining case, each of  $\Gamma(B^1)$  and  $\Gamma(B^2)$  has nonempty intersection with both  $C^1$  and  $C^2$ , and hence  $b^* = 2b$ . If further every vertex in  $B^1 \setminus \{\alpha\}$  has neighbours in both  $C^1$  and  $C^2$ , then  $v^* = k^* + 1$ ,  $r^* = 2r$  and  $s^* = s/2$ , and so case (b)(ii) occurs. If not every vertex in  $B^1 \setminus \{\alpha\}$  has neighbours in both  $C^1$  and  $C^2$ , then by symmetry the numbers of vertices in  $B^1 \setminus \{\alpha\}$  having neighbours in  $C^1$  and  $C^2$  are equal. This implies that

$$k^* = (v^* - 1)/2$$
,  $r^* = b^* k^* / v^* = b(v - 2)/v = r$  and  $s^* = rs/r^* = s$ ,

and hence case (b)(iii) occurs.

Example 2.4 in [2] can serve as an example for case (a) in Theorem 2 when v = 3. Examples for case (b)(i) when v = 4 can be obtained from [4, Construction 3.2]: let M be a regular map on a closed surface such that its underlying graph  $\Sigma$  has valency four. (A regular map is a 2-cell embedding of a connected (multi)graph on a closed surface such that its automorphism group is regular on incident vertex–edge–face triples.) For each edge { $\sigma$ ,  $\sigma'$ } of  $\Sigma$ , let f and f' denote the faces of M with { $\sigma$ ,  $\sigma'$ } as a common edge. Denote by  $f_{\sigma}$  and  $f'_{\sigma}$  the other two faces of M incident with  $\sigma$  and opposite to f and f' respectively, and define  $f_{\sigma'}$  and  $f'_{\sigma'}$  similarly. Let  $\Gamma_1(M)$ ,  $\Gamma_2(M)$ ,  $\Gamma_3(M)$  and  $\Gamma_4(M)$  be the graphs [4] with vertices the incident vertex–face pairs of M and

[4]

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adjacency defined as follows (where ~ means adjacency): for each edge { $\sigma, \sigma'$ } of  $\Sigma$ ,  $(\sigma, f) \sim (\sigma', f)$  and  $(\sigma, f') \sim (\sigma', f')$  in  $\Gamma_1(M)$ ;  $(\sigma, f) \sim (\sigma', f')$  and  $(\sigma, f') \sim (\sigma', f)$  in  $\Gamma_2(M)$ ;  $(\sigma, f_{\sigma}) \sim (\sigma', f_{\sigma'})$  and  $(\sigma, f'_{\sigma}) \sim (\sigma', f_{\sigma'})$  in  $\Gamma_3(M)$ ;  $(\sigma, f_{\sigma}) \sim (\sigma', f_{\sigma'})$  and  $(\sigma, f'_{\sigma'}) \sim (\sigma', f_{\sigma'})$  and  $(\sigma, f'_{\sigma}) \sim (\sigma', f_{\sigma'})$  and  $(\sigma, f'_{\sigma}) \sim (\sigma', f_{\sigma'})$  in  $\Gamma_4(M)$ . These graphs are *G*-symmetric [4, Lemma 3.3] and admit  $\mathcal{B} := \{B(\sigma) : \sigma \in V(\Sigma)\}$  as a *G*-invariant partition, where  $B(\sigma) = \{(\sigma, f) : \sigma$  incident with  $f\}$ , such that k = v - 2 = 2,  $\Gamma_B \cong \Sigma$ ,  $\Gamma^{B(\sigma)} = K_{2,2}$  and  $\Gamma[B(\sigma), B(\tau)] = 2 \cdot K_2$  for adjacent  $B(\sigma)$ ,  $B(\tau) \in \mathcal{B}$ . These four graphs fall into case (b)(i) in Theorem 2 and the *G*-invariant partition induced by the bipartition of  $\Gamma^{B(\sigma)}$  is  $\mathcal{B}^* := \{B^1(\sigma), B^2(\sigma) : \sigma \in V(\Sigma)\}$ , where  $B^1(\sigma) = \{(\sigma, f), (\sigma, f_{\sigma})\}$  and  $B^2(\sigma) = \{(\sigma, f'), (\sigma, f'_{\sigma})\}$ .

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