

# Sensitivity functions and uncertainty analysis

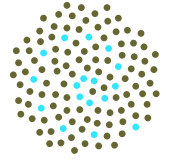
Ian G. Enting

MASCOS

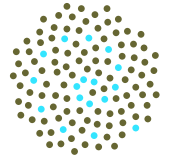
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# Acknowledgments



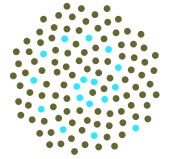
- The Center of Excellence for Mathematics and Statistics of Complex Systems (MASCOS) is funded by the Australian Research Council (ARC).
- My fellowship at MASCOS is supported by CSIRO through a sponsorship agreement.
- Collaborators: Cathy Trudinger and YingPing Wang of CSIRO Marine and Atmospheric Research and members of the MATCH working group on the Brazilian Proposal.



# Summary

- Analysing the Brazilian proposal
  - Marginal attribution
  - Sensitivity functions
  - Use in attribution, sensitivity and data uncertainty
- Interpretation as adjoints
- derivation by automatic differentiation.

# Brazilian Proposal



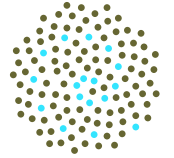
Tabled by Brazil during negotiations leading to Kyoto Protocol — Flicked-passed to Subsidiary Body for Scientific and Technical Advice (SBSTA).

Proposes that emission reduction targets should be proportional to nation's relative responsibility for the greenhouse effect.

Issues:

- Indicator? What quantity is used as a measure of the greenhouse effect?
- For what period of emissions is responsibility attributed?
- How are non-linear responses attributed?

# Marginal attribution



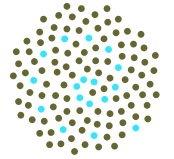
As example, use indicator  $T^* = T_{\text{CO}_2}(2100) =$  warming in 2100 from  $\text{CO}_2$  emissions.

$T^*$  is to be attributed to emissions  $E_j(t)$  from country  $j$  with  $E(t) = \sum_j E_j(t)$ .

Differential attribution of warming to emissions from country  $j$  is

$$\frac{\partial}{\partial \alpha_j} T^* \left[ \sum_j (1 + \alpha_j) E_j(t) \right]$$

# Sensitivity functions



Consider additive form:  $\frac{\partial}{\partial \gamma} T^*[E(t) + \gamma f(t)]$

This is linear:  $\frac{\partial}{\partial \gamma} T^*[E(t) + \gamma(f_1(t) + f_2(t))]$

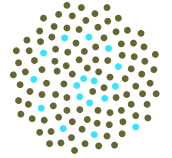
$$= \frac{\partial}{\partial \gamma} T^*[E(t) + \gamma f_1(t)] + \frac{\partial}{\partial \gamma} T^*[E(t) + \gamma f_2(t)]$$

Therefore can be represented as inner product:

$$\frac{\partial}{\partial \gamma} T^*[E(t) + \gamma f(t)] = \int_0^T S(t) f(t) dt$$

Sensitivity function,  $S(t)$  is Frechet derivative.

# Applications



- Attribution

$$\frac{\partial}{\partial \alpha_j} T^* [\sum_j (1 + \alpha_j) E_j(t)] = \int S(t) E_j(t) dt$$

- Cumulated attribution:  $T_j^* = \sum_j \int S(t) E_j(t) dt$

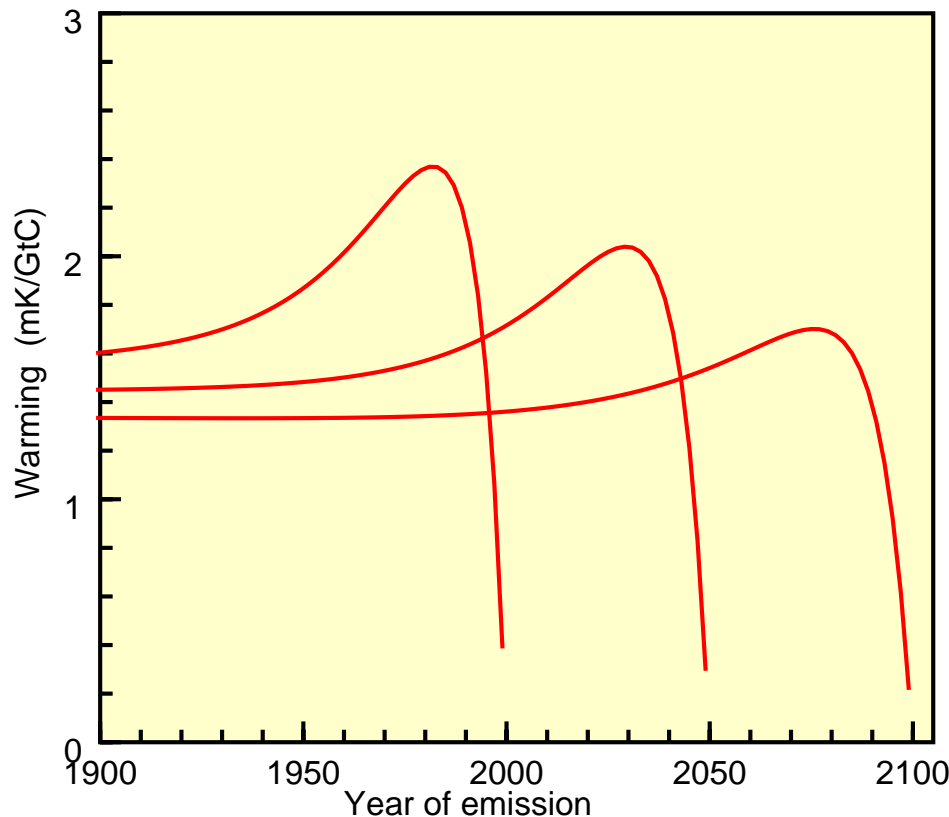
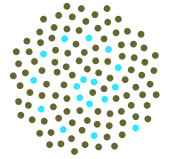
- Sensitivities:

$$\frac{\partial}{\partial \beta} T_j^* = \sum_j \int E_j(t) \frac{\partial}{\partial \beta} S(t) dt$$

- Sensitivity of  $T_j^*$  to uncertainties in emissions can be obtained as

$$\text{Var}[T_j^*] = \int \int S(t) \text{Cov}[E_j(t), E_j(t')] S(t') dt' dt$$

# Results: Frechet Derivatives

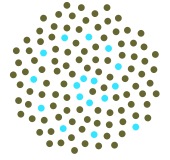


Assumes IS92a emissions. Represents temperature by response function. Linear responses for ocean and biotic carbon, coupled non-linearly to atmospheric CO<sub>2</sub> (as in CSIRO study).

“ $\frac{\partial}{\partial E(t)} T(\tau)$ ” for  $\tau = 2000, 2050, 2100$ .

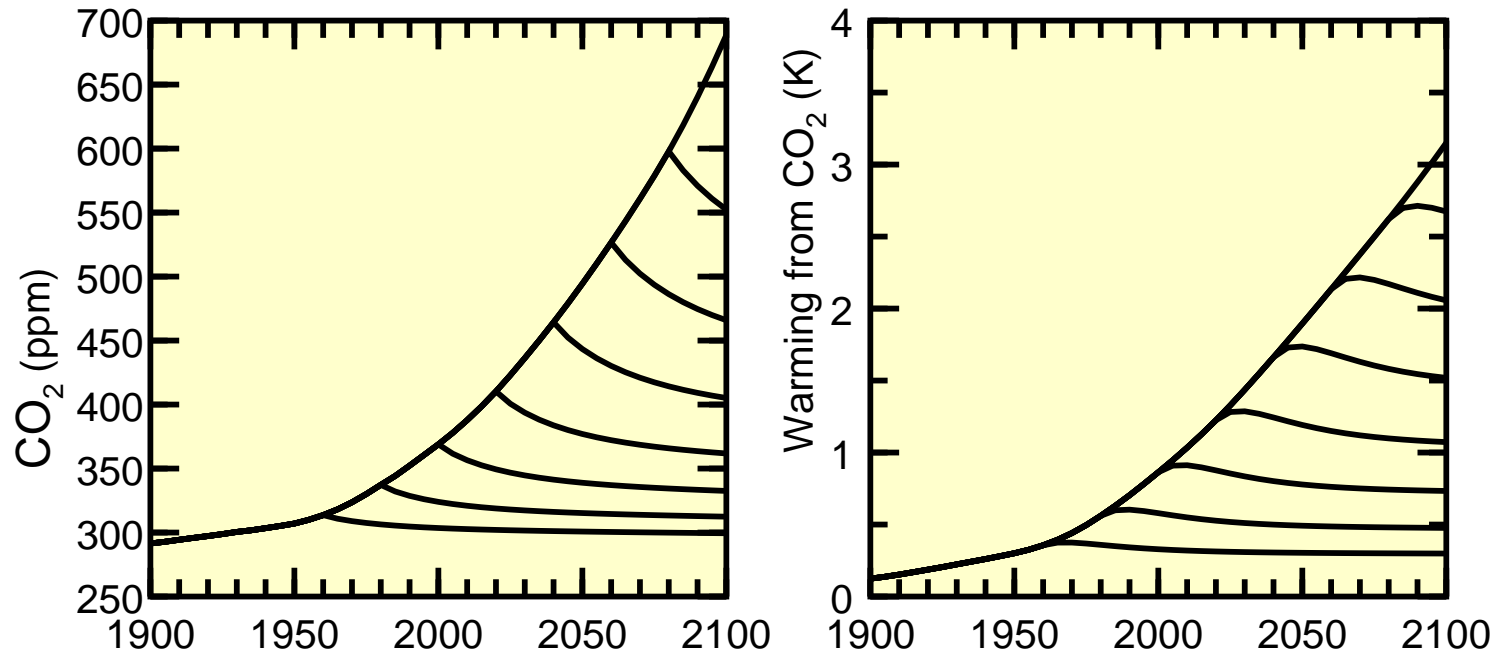
Decrease as  $t \rightarrow \tau$  shows ‘committed warming’. At any time, warming from the most recent releases is yet to happen.





# Timescales

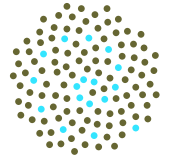
CO<sub>2</sub> concentrations and consequent warming, partitioned according to time of emission.



Lowest bands are from pre-1960 emissions, next from 1960 to 1980 emissions, etc.

Increase in contribution to warming after time of emissions from 'committed warming' effect.

# Tangent Linear Model (TLM)



For  $N$  DEs:  $\frac{d}{dt}x_j = g_j(\{x_k\}, \alpha, t)$  for  $j = 1, N$

we can define sensitivities as

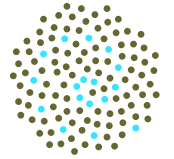
$$y_{j,p} = \frac{\partial}{\partial \alpha_p} x_j \quad \text{for } j = 1, N \text{ or}$$

to give 'tangent linear model(s)':

$$\frac{d}{dt}y_{m,p} = \frac{\partial}{\partial \alpha_p} g_m(\{x_k\}, \alpha, t) + \sum_n \frac{\partial}{\partial x_n} g_m(\{x_k\}, \alpha, t) y_{n,p}$$

Adjoint relations can give gradients.

# Algorithmic Differentiation (AD)



Differentiation by successive use of chain rule.

For binary operation  $c = f(a, b)$ ,

$$\frac{\partial c}{\partial \alpha} = \frac{\partial f}{\partial a} * \frac{\partial a}{\partial \alpha} + \frac{\partial f}{\partial b} * \frac{\partial b}{\partial \alpha}$$

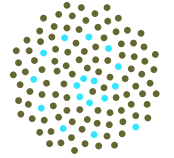
e.g.

$$c = a + b \quad \rightarrow \quad \frac{\partial c}{\partial \alpha} = \frac{\partial a}{\partial \alpha} + \frac{\partial b}{\partial \alpha}$$

$$c = a * b \quad \rightarrow \quad \frac{\partial c}{\partial \alpha} = b * \frac{\partial a}{\partial \alpha} + a * \frac{\partial b}{\partial \alpha}$$

Convert program to code for derivatives, one operation at a time.

# Operator Overloading (C++)



Replace real variable  $x$ , (type `double`), with composite variable  $\tilde{x}$  (type `Xvar`), representing both value  $x$  and its derivatives with respect to  $K$  model quantities,  $\alpha_k$  as:

$$\tilde{x}_0 = x \quad \text{and} \quad \tilde{x}_k = \frac{\partial}{\partial \alpha_k} x \quad \text{for } k = 1, K$$

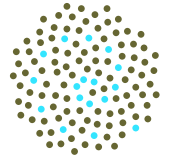
Operator overloading implements  $\tilde{c} = \tilde{a} * \tilde{b}$ , representing:

$$\tilde{c}_0 = \tilde{a}_0 * \tilde{b}_0 \quad \text{and} \quad \tilde{c}_k = \tilde{a}_0 * \tilde{b}_k + \tilde{a}_k * \tilde{b}_0$$

Overloaded functions,  $\tilde{c} = f(\tilde{a})$ , represent:

$$\tilde{c}_0 = f(\tilde{a}_0) \quad \text{and} \quad \tilde{c}_k = f'(\tilde{a}_0) * \tilde{a}_k$$

where  $f'(\cdot)$  denotes the derivative of  $f(\cdot)$



# Class Definitions

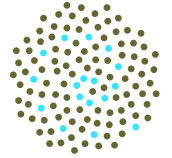
Fragment of C++ class definition to implement operator overloading:

```
class Xvar{
public :
static const int ns = _NUMDERIVS+1;
double xs[_NUMDERIVS+1];
Xvar operator*(Xvar);
...
};

Xvar Xvar::operator*(Xvar b){ Xvar c;
for (int i=1; i < ns; i++)
    c.xs[i] = xs[i]*b.xs[0]+xs[0]*b.xs[i];
c.xs[0] = xs[0]*b.xs[0];
return c;} ;
...
```

In preparation for MATCH workshop

# Usage

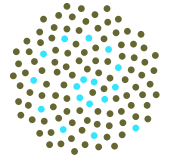


## Original

```
double F_co2(double c){
double a;
a = log(c/280.0)*5.35;
return a;
};
...
double cc;
...
ff = F_CO2(cc)
```

## Transformed

```
Xvar F_co2(Xvar c){
Xvar a;
a = log(c/280.0)*5.35;
return a;
};
...
Xvar cc;
// Derivatives wrt
// initial value of cc
cc.set(280,1);
...
ff = F_CO2(cc)
```



# Putting AD into models

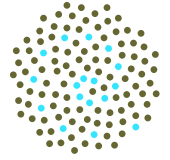
Need to modify model by changing:

- type declarations
- output
- initialisation (and input)
- other surprises ????

Use syntax checking of compiler to help ensure validity.

*Real = x\_var* should be undefined, detection by compiler implies failure to declare all necessary variables.

# Basic Operator Requirements



A basic set:

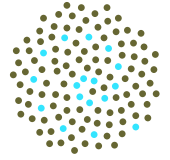
| Op | Binary |        |        |        |        |
|----|--------|--------|--------|--------|--------|
|    | X.op.X | R.op.X | X.op.R | X.op.I | I.op.X |
| =  | Y      | N/A    | Y      | Y      | N/A    |
| +  | Y      | Y      | Y      | Y      | Y      |
| -  | Y      | Y      | Y      | Y      | Y      |
| *  | Y      | Y      | Y      | Y      | Y      |
| /  | Y      | Y      | Y      | Y      | Y      |
| ** | -      | -      | -      | Y      | -      |

Unary operations (and intrinsics)

| Op | - | sqrt | cos | sin | log | exp |
|----|---|------|-----|-----|-----|-----|
|    | Y | Y    | Y   | Y   | Y   | Y   |



# Conclusions



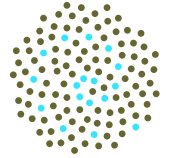
## Brazilian Proposal —

- For a given indicator,  $T^*$ , calculation of  $S(t)$  allows attribution to any nation.
- $S(t)$  most efficiently calculated from adjoint model, but for multiple indicator times, tangent linear model is not too inefficient.
- Sensitivity of  $T_j^*$  to model uncertainties can be obtained as second derivatives.

## Algorithmic differentiation —

Operator overloading is a straightforward way of developing tangent linear models (and obtaining higher derivatives if needed).

# Further Information



Andreas Griewank, 2000, *Evaluating Derivatives: Principles and Techniques of Algorithmic Differentiation*, (SIAM, Philadelphia).

MATCH website (Brazilian Proposal):  
<http://www/match-info.net>

I.G. Enting, 2005, *Automatic differentiation in the analysis of strategies for mitigation of global change*, International Congress on Modelling and Simulation, Melbourne, 2005. Ed. A. Zenger and R. M. Argent, 7pp  
<http://www.mssanz.org.au/modsim05/papers/enting.pdf>